

## IMAGE ENHANCEMENT USING MATLAB

Kirti Agrahari<sup>1</sup>, Diksha Srivastava<sup>2</sup>, Purnima Tripathi<sup>3</sup>

<sup>1,2,3</sup>Department of Electronic and Communication,  
Engineering Buddha Institute of Technology Gida Gorakhpur (India)

### ABSTRACT

*With rapid growth of human-computer interaction, more and more useful software are replacing human efforts. This paper integrates the idea to process an image for reduction of image size and enhancement of image as per our application. Reduction in salt and pepper noise is also proposed in the present work. Quality of the image is not satisfactory in many cases to find out the meaningful information. As all enhancement techniques are application oriented, it is necessary to find a method which needs simple operations with effective enhancement and does not require complex operations like logarithmic, exponential, Probability Density Function. We can remove noise from image, detect the edge of image, convert the rgb image into binary etc. The noise destroys the original image quality by changing the true pixel value. So for reduction of noise from an original image it is very much essential to distinguish the type of noise, its effect in an image and its reduction technique. The proposed method provides good results subjectively as well as objectively for both gray scale and true colour images. The proposed method is useful for interactive image processing applications as it has a family of possible transformations for various enhancement levels.*

**Keywords:** *Image enhancement (IE), Digital image processing (DIP), Probability density function (PDF).*

### I. INTRODUCTION

The image enhancement is a technique or in other words process of adjusting the digital images and the resultant image which we get are more suitable for display. The aim of image enhancement is to improve the perception of information in image for human viewers and also for other automated image processing technique. It is a method to perform an operation on an image, in order to get an enhanced image and extract some information to it. In this image processing, the input is an image and output may be the special characteristics associated with that particular image. For this purpose MATLAB is a very powerful tool. MATLAB is developed by Math works and it is a high performance language to do programming in easy-to-use environment. The main advantage of MATLAB is its numerical precision is very high. different technique will applied pixel to pixel to perform so many task- like converting a image into Black and white., binary image, negative of an image, increasing its brightness, edge detection, removing salt and pepper noise etc. An image is supposed to provide information to the human viewers. Computers are faster and more accurate than human beings in processing numerical data. However, human beings score over computers in recognition capability. Human beings use all the five sensory organs to gather information

about the outside world. The old Chinese proverb 'A picture speaks a thousand words' rightly points out that the images are very powerful tools to provide information to the viewers in every field i.e., medical images for doctors, forensic images for police investigation, text images for readers etc. In the process of image acquisition, image clarity is affected by lighting, weather, distance, or equipment used for image capture. Enhancement basically improves visual quality by providing clear images for human observer and/or for machine in automatic processing techniques.

The system we propose in this paper integrates the idea to process an image for reduction of image size and enhancement of image as per our application. The proposed work describes the method of accessing every picture element of an image using Matlab. Different Enhancement techniques will be applied pixel to pixel to perform various tasks.

And they are described below –

## 1.1. **Black & white image:**

A black and white image means that the image has the maximum range up to  $2^n$ , starting from 0 to  $2^n$  (where n is number of bit / bits in one pixel). This is also called a gray scale image. Black and white image has pure black means 0 up to pure white means  $2^n$ . for example- if one pixel have 8 bits than the values are in between 0 (pure black) to 255 (pure white). The BW (Black and White) image and Binary image both are different with each other as we can see in the following images.

## 1.2. **Binary image :**

A binary image is a digital image that has only two possible values of each pixel. Typically, the two colours used for binary image are black and white, though any two colours can be used. The colour used for the object(s) in the image is foreground colour while the rest of the image is the background colour. Binary images are also called bi-level or two-level. This means that each pixel is stored as a single bit i.e., 0 (black) or 1 (white).

## 1.3. **Negative of an image:**

Negative of an image is also called complement of that image. In the complement of binary images zeros becomes ones and ones become zeros; black and white are reversed. The complement of an intensity or RGB image, each pixel value is subtracted from the maximum pixel value supported by the class (or 1.0 for double precision images) and the difference is used as the pixel value in the output image. In the output image dark areas are become lighter and light areas are become darker.

## 1.4. **Brightness of an image:**

Customized brightness of an image means to enhance the brightness of the image so that it looks clear and attractive. In customized brightness of an image we can change the image contrast and brightness of the image.

## 1.5. **Edge detection:**

Edge detection is a technique for finding the boundaries of objects within images. It works by detecting discontinuities in brightness. Edge detection is used for image segmentation and data extraction in areas such as

image processing, computer vision and machine vision. In an image, an edge is a curve that follows a path of rapid change in image intensity.

## 1.6. Removing salt and pepper noise of an image:

Salt and paper noise is form of noise sometimes seen on images. It presents itself as sparsely occurring white and black pixels. An effective noise reduction method for this type of noise is a median filter or a morphological filter.

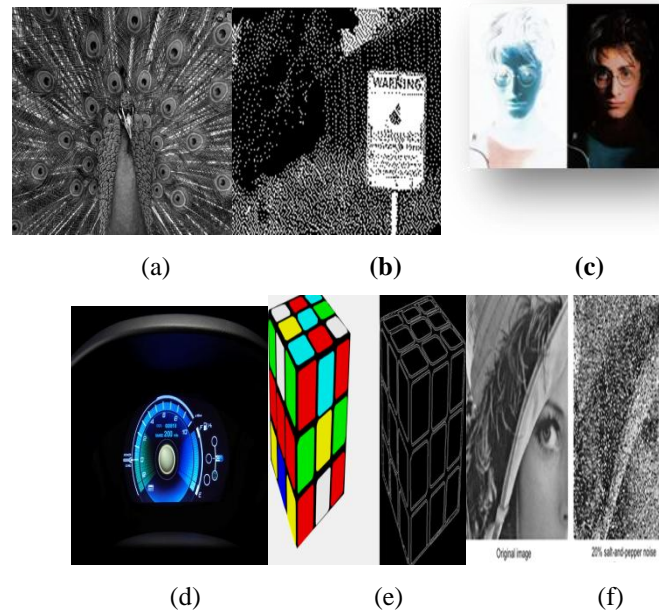


Fig 1: (a) A Black & White image, (b) A binary image, (c) Negative of an image, (d) A customized brightness in an image, (e) Edge detection of an image, (f) Removal of Salt and pepper noise of an image.

## III. INDENTATIONS AND EQUATIONS

Some equations that are used in the programming are given below-

### 1. For loading image :

```
global im im2  
[Path]=imgetfile();
```

### 2. For binary image :

```
global im  
a=im2bw(im);
```

### 3. For gray image :

```
global im  
imgray=(im(:, :, 1)+im(:, :, 2)+im(:, :, 3))/3;
```

### 4. For sliders:

```
a). global im2  
val=2*get(hObject,'value');
```

```
ibt=im2+val;  
b). global im  
val=get(hObject,'value');  
c==(im(:,:,1)+im(:,:,2)+im(:,:,3))/val;
```

## IV. FIGURES AND TABLES

The enhanced result show that after converting the images, we meet up with certain advantages, like converting RGB image to binary image, black and white and negative of an image ,the output image which we get will visible to us with their contrast values. One can decide its own value and can get special effects in an image. Moreover, brightness of an image, edge detection and removing salt and pepper noise will help to increase the effectiveness of an image in terms of clearing the image without any noise because noise are in form of small black and white dots present on an image making it unclear. It is also use for data hiding techniques.

### Black & White image



Fig. 2.1: Black and White image

### Discussion

There is reduction in memory size after converting in image, the reduction in memory size can be seen in the above diagram. It helps in data saving. In gray scale images whole object is visible to us with their contrast values in black and white (0 -255 for 8 bit size of one pixel)

### Binary image:



Fig. 2.2: Binary image

### Discussion

There is reduction in memory size after converting in image, the reduction in memory size can be seen in the above diagram. It helps in data saving. For example - If in a traffic system we want to note the numbers of vehicles then there is no means of the colours and designs of the number plate of vehicles before recognizing it in the camera, first we convert it in binary so that it can detect the number and then start our further process. We can decide our own offset value according to us.

**Negative of an image**

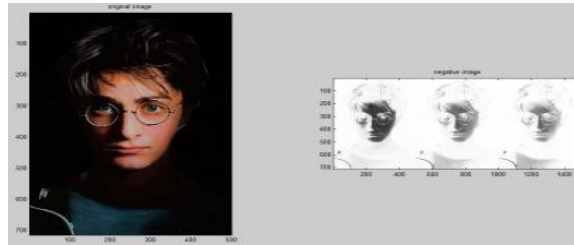


Fig. 2.3: Negative of an image

**Discussion**

There is reduction in memory size after making negative of an image, the reduction in memory size can be seen in the above diagram. We use negative effect in focusing the primary objects more than secondary objects. This is called special effects and these are also used in DSLR cameras these days most. It slightly blurs the secondary objects than primary that are also seen these days in wedding images, and movies etc. Negative of any image is just complement of the original image means the pixel values get subtracted from the maximum value.

**Edge Detection**



Fig. 2.4: original image

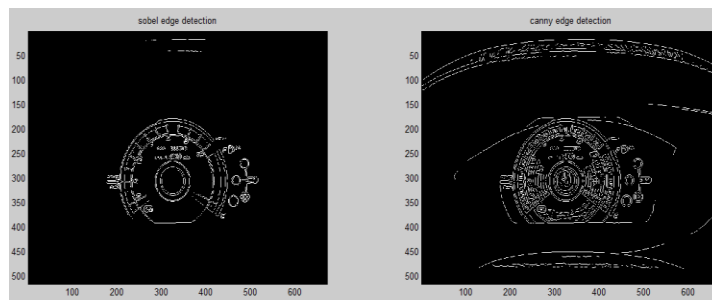


Fig. 2.5: Different type of edge detection images

**Discussion**

There is reduction in memory size in finding the edges of any image, this memory sizes can be seen in the above diagram. It helps us to recognize those images which are not visible clearly. This can be determining after finding the edges of that particular image. Edge detection is one of the initial steps to detect vehicles on road for analyzing behaviour of the vehicles. Edge detectors are also used in face recognition, x – rays etc.

**Brightness of an image**

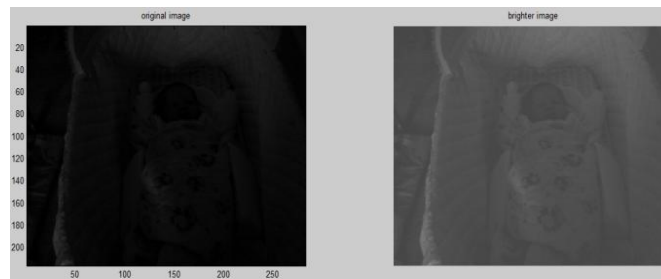


Fig. 2.6 Bright image with its original image

**Discussion**

There is no reduction in memory size in increasing brightness of the image; this memory size can be seen in the above diagram. It helps us to see those images which are not visible clearly. Customized brightness are used in LCDs, LEDs and mobile phone display etc

**Removal of salt and pepper noise**

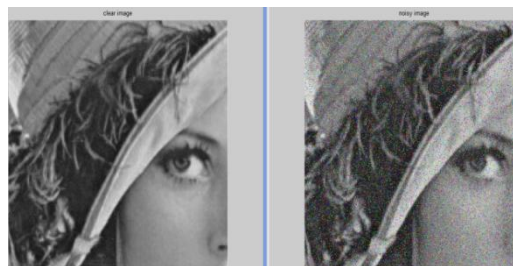


Fig. 2.7: Salt and pepper noise with its clear image

**Discussion**

If unwanted information comes on your image in the form of dots (basically black & white), they are not information's they are noise on that image and that are called salt and pepper. There is reduction in memory size in removing salt and pepper noise from any image, this memory size can be seen in the above diagram. It helps us to see those images which are not visible clearly .Salt and pepper noise images are also used for data hiding.

Tabular & Graphical representation of above results is as follows –Table

	Size of Input image (KB)	Size of output image (KB)	Reduced size (KB)
Black & White	55.81	18.6	37.2
Binary	1013.9	468.75	545.15
Negative	1049.45	0.1834	1049.274
Edge detection	1013.9	337.968	675.93
Brightness	559.695	179.085	-119.39
Removal of salt & pepper noise	759.026	759.026	0

Fig. 3.1: Tabular representation of memory sizes

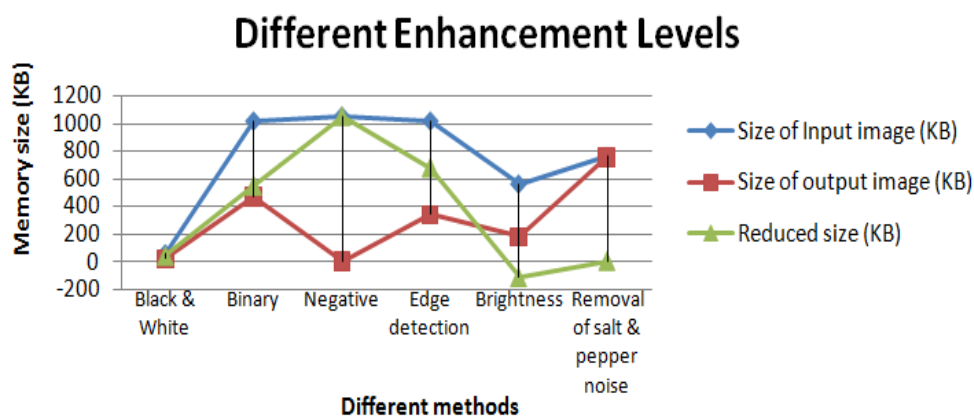


Fig. 3.2: Graphical representation of different memory sizes of input and output image sizes with their reduced memory size

## V. CONCLUSION

This technique gives us freedom to decide own offset value according to user that means it provide flexibility to a user. The resultant image will change according to the offset value. For further advancement of this signal processing technique we can make a GUI(Graphical user interface) in which the image will convert as per the user press the push buttons and will get the respective results instantly.



Fig. 4.1: An image of a GUI

The following conclusions are -

From above we conclude that all the tasks that we perform in this project are gives us freedom to decide the offset value at which we want to enhance the image. There is reduction in memory size of the image in every enhancement process. There is only need of information from any image so we have applied the above tasks on an image to reduce memory. Here end user can access according to him / her... If we buy software for different enhancements techniques then there is fixed offset level so if we want to enhance the image at our offset value then we can't do .After performing these tasks according to us we can save data also according to us more and more and this will depend on offset value that we decide. We use negative effect in focusing the primary objects more than secondary objects. This is called special effects and these are also used in DSLR cameras these days most. It slightly blurs the secondary objects than primary that are also seen these days in wedding images, and movies etc. By deciding the offset value the appearance of primary objects is clearer.

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## VII. FUTURE SCOPE

Continuously increment in computing power of implementation platforms, executed under real time constraints. Real time application may consist of different image standards, or different algorithms used at different stages of the processing chain... The computing paradigm using Reconfigurable architectures promises an intermediate trade-off between flexibility and performance. We can prepare a **Graphical User Interface (GUI)**. In which we can apply offset value directly by push buttons on our GUI and will get the respective results instantly with their respective Histograms.

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